THE PERIOD MATRIX OF THE HYPERELLIPTIC CURVE

 $w^2 = z^{2g+1} - 1$

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ABSTRACT. We introduce a geometric algorithm for finding a symplectic basis of the first integral homology group of a compact Riemann surface which is a p-cyclic covering of $\mathbb{C}P^1$ branched over 3 points. It gives us an unknown symplectic basis of the hyperelliptic curve defined by the affine equation $w^2 = z^{2g+1} - 1$ for genus $g \geq 2$. Moreover, we explicitly obtain the period matrix of this curve whose all entries are elements of the (2g+1)-st cyclotomic field.

1. Introduction

Let X be a compact Riemann surface of genus $g \geq 2$ or smooth projective algebraic curve over \mathbb{C} . The period matrix τ_q of X depends only on the choice of a symplectic basis of the first integral homology group $H_1(X;\mathbb{Z})$. It is known that τ_q is symmetric and its imaginary part is positive definite. The Jacobian variety J(X) of X is defined by a complex torus $\mathbb{C}^g/(\mathbb{Z}^g + \tau_q \mathbb{Z}^g)$. Torelli theorem says that two given Riemann surfaces X and Y are biholomorphic if and only if J(X) and J(Y) are isomorphic as polarized abelian varieties. It implies τ_g determines the complex structure of X. In general, it is not easy to calculate τ_q , in particular, find a symplectic basis of $H_1(X;\mathbb{Z})$. Tretkoff and Tretkoff [17] gave a method of computation of τ_q , using Hurwitz systems. Bene [3] showed a way of finding a symplectic basis of $H_1(X;\mathbb{Z})$ by means of *chord* slides for linear chord diagrams. By combining these two methods, we explicitly write down a geometric algorithm for finding a symplectic basis of the first integral homology groups of p-cyclic coverings of $\mathbb{C}P^1$ branched over 3 points for prime number $p \geq 5$. Furthermore we explain calculating the period matrix this kind of Riemann surfaces. We compute the period matrices of the hyperelliptic and Klein quartic curve defined by the affine equations $y^7 = x(1-x)$ and $y^7 = x(1-x)^2$ respectively.

For generic genus, few examples of period matrices are known. Schindler [13] computed the period matrices of three types of hyperelliptic curves of genus $g \geq 2$. These are the unique examples as far as we know. Kamata [10] introduced an algorithm for calculating those of Fermat type curves. For low genus case, see [6], [7], and their references. We remark that Streit [14] studied about the period matrices from viewpoints of representation theory. For any odd number $q \geq 5$, let $C_{q,1}$ be the smooth projective curve over $\mathbb C$ defined by the affine equation $y^q = x(1-x)$. This is biholomorphic to the hyperelliptic curve defined by the affine equation $w^2 = z^{2g+1} - 1$ of genus g = (q-1)/2. Tashiro, Yamazaki, Ito, and Higuchi [16] computed the periods on $C_{q,1}$. We obtain the period matrix τ_g of $C_{q,1}$ using the inverse of the Vandermonde matrix. Schindler [13] obtained one of the same hyperelliptic curve of genus $g \geq 2$ defined by the affine equation $w_1^2 = z_1(z_1^{2g+1} - 1)$. This result contains a recurrence relation. On the other side, we have an explicit representation of it. Set $\zeta = \zeta_q = \exp(2\pi\sqrt{-1}/q)$. A symplectic

basis $\{A_i, B_i\}_{i=1,2,...,g}$ of $H_1(C_{q,1}; \mathbb{Z})$ is defined later. For variables $x_1, x_2, ..., x_n$, we denote by $\sigma_i(x_1, x_2, ..., x_n)$ the symmetric polynomial

$$\sum_{1 \le j_1 < \dots < j_i \le n} x_{j_1} \cdots x_{j_i}$$

for $1 \le i \le n$ and $\sigma_0(x_1, x_2, ..., x_n) = 1$.

Theorem 4.5. We have the period matrix τ_g of $C_{q,1}$ with respect to the symplectic basis $\{A_i, B_i\}_{i=1,2,...,q}$

$$\tau_g = \left(\sum_{k=1}^g \frac{(-1)^{i+g}}{2g+1} (1 - \zeta^{2kj}) \sigma_{g-i}(\zeta^2, \zeta^4, \dots, \widehat{\zeta^{2j}}, \dots, \zeta^{2g}) \prod_{m=g-k+1}^{2g-k} (1 - \zeta^{2m}) \right)_{i,j},$$

where the 'hat' symbol $\hat{}$ over ζ^{2j} indicates that this element is deleted from the sequence $\zeta^2, \zeta^4, \ldots, \zeta^{2g}$.

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2. Algorithm

In this section, we write down a geometric algorithm for finding a symplectic basis of the first integral homology groups of smooth projective algebraic curves defined by the affine equation $y^p = x^l(1-x)^m$. Here $p \geq 5$ is prime number, l, m are coprime, and $1 \leq l, m, l+m < p$. We denote this curve by $X_{p,l,m}$. This is a Riemann surface of genus g = (p-1)/2 and can be considered as a p-sheeted cyclic coverings of $\mathbb{C}P^1$ branched over $\{0,1,\infty\}\subset \mathbb{C}P^1$. In particular, we simply write the curve $X_{p,1,m}=C_{p,m}$ for the case l=1. Through this section, we use an example: the Klein quartic $C_{7,2}$. Moreover, we explain calculating the period matrix of $X_{p,l,m}$ using holomorphic 1-forms of Bennama and Carbonne [5]. It is known that there are only two $X_{7,l,m}$ up to isomorphism for

the case p = 7. They are $C_{7,1}$ and $C_{7,2}$. See [8, §1.3.2] for example. We calculate the period matrices of them.

2.1. **Dessins d'enfants.** Let X be a smooth projective algebraic curve over a field k. We assume that k is \mathbb{C} and there exists a covering $\pi\colon X\to\mathbb{C}P^1$ branched over $\{0,1,\infty\}\subset\mathbb{C}P^1$. The inverse image $\pi^{-1}([0,1])$ in X of the unit interval in $\mathbb{C}P^1$ is called dessins d'enfants [9]. It is a topological bipartite graph illustrated on the Riemann surface X. Belyi [2] proved that all the algebraic curves over $\overline{\mathbb{Q}}$ correspond to the dessins d'enfants. The map π is often called Belyi map. See also [18]. In the rest of this paper, we simply assume that X is $X_{p,l,m}$ and $\pi\colon X\ni (x,y)\mapsto x\in\mathbb{C}P^1$ is a p-cyclic covering branched over $\{0,1,\infty\}\subset\mathbb{C}P^1$. Set the order p holomorphic automorphism $\sigma(x,y)=(x,\zeta_py)$. Here, we denote $\zeta_p=\exp(2\pi\sqrt{-1}/p)$. Let $y_0(t)$ is a real analytic function $\sqrt[p]{t^l(1-t)^m}$. A continuous path $I_0\colon [0,1]\to X$ is defined by the equation $I_0(t)=(t,y_0(t))\in X$ for $0\leq t\leq 1$. Immediately we obtain $\pi(I_0)=[0,1]\subset\mathbb{C}P^1$ and the dessin d'enfants $\pi^{-1}([0,1])=\bigcup_{i=0}^{p-1}\sigma_i^i(I_0)$. We call $\pi^{-1}(0)$ and $\pi^{-1}(1)$ the white and black vertex respectively. The dessin $\pi^{-1}([0,1])$ in X is a bipartite graph. Take a point b_i on the $\sigma_i^i(I_0)$ except for endpoints for each i. For the Klein quartic $C_{7,2}$, We draw the dessin d'enfants $\pi^{-1}([0,1])$. See Figure 1.

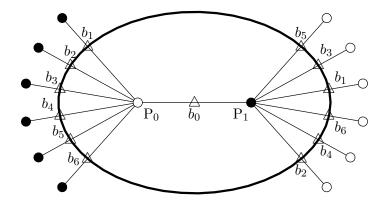


FIGURE 1. A dessin d'enfants of the Klein quartic $C_{7,2}$

2.2. **Intersection numbers.** We introduce the method of Tretkoff and Tretkoff [17], called Hurwitz system, from dessins d'enfants to the intersection numbers of the loops in X. First, we explain the definition of a chord diagram. A chord diagram is defined by a union of a unit circle S^1 and 2g = p - 1 simple chords. It satisfies the endpoints of the chords attached to S^1 and each arc intersects at most one points. If the chord diagrams are oriented, we call it an oriented chord diagram.

For $i=1,2,\ldots,p-1$, let c_i denote the loop $I_0 \cdot \sigma_*^i(I_0)^{-1}$ in X. Here, the product $I_0 \cdot \sigma_*^i(I_0)^{-1}$ indicates that we traverse I_0 first, then $\sigma_*^i(I_0)^{-1}$. It follows that the dessin d'enfants $\pi^{-1}([0,1])$ equals to the union $\bigcup_{i=0}^{p-1} c_i$. We deform the dessin topologically and consider c_i as not loops but chords. We get an oriented chord diagram and compute the intersection numbers $c_i \cdot c_j = 0$ or ± 1 . Let $(a_{i,j})_{i,j}$ denote the matrix whose (i,j)-th

entry is $a_{i,j}$. If the $2g \times 2g$ intersection matrix $(c_i \cdot c_j)_{i,j}$ is regular, then $\{c_i\}_{i=1,2,...,2g}$ is a basis of the first integral homology group $H_1(X;\mathbb{Z})$.

For $C_{7,2}$, we obtain the oriented chord diagram in Figure 2 which corresponds to Figure 1. For convenience sake, the origin and terminal point of c_i is denoted by i and \bar{i} respectively. The intersection matrix is as follows [17, pp. 482]

$$\begin{pmatrix}
0 & 0 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 1 & 1 & 1 \\
-1 & -1 & 0 & 0 & 1 & 0 \\
0 & -1 & 0 & 0 & 1 & 1 \\
-1 & -1 & -1 & -1 & 0 & 0 \\
0 & -1 & 0 & -1 & 0 & 0
\end{pmatrix}.$$

We can take many bases of $H_1(X;\mathbb{Z})$. For example, we [15] chose another basis $\{\ell_i\}_{i=1,2,\dots,6}$ such that $\ell_i=c_{i-1}\cdot c_i^{-1}$ for $C_{7,2}$.

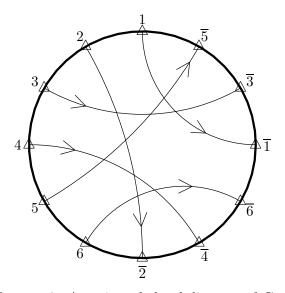


FIGURE 2. An oriented chord diagram of $C_{7,2}$

2.3. **Linear chord diagrams.** Using Bene's method [3], we identify oriented chord diagrams with oriented linear chord diagrams. We define a linear chord diagram in the plane with k chords in the following way. It is the interval [0, 2k], together with k simple arcs in the upper half plane whose endpoints are attached to the interval at the integer points $\{1, 2, \ldots, 2k\}$. If the linear chord diagrams are oriented, we call it an oriented linear chord diagram.

Cut open at a certain point on S^1 in an oriented chord diagram in the subsection 2.1. By identifying 2g chords with loops $\{c_1, c_2, \ldots, c_{2g}\}$, we have the oriented linear chord diagram. Since the intersection number $c_i \cdot c_j$ is independent from the choice of cutting points, we may choose any those points. For $C_{7,2}$, choose a point $\overline{6}$ in Figure 2. Then we have an oriented linear chord diagram in Figure 3.

2.4. Chord slides. Bene [3, § 8] used chord slides for the oriented linear chord diagrams. He studied about chord slides with the Whitehead moves on the fatgraphs

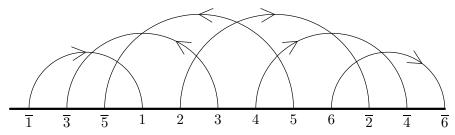


FIGURE 3. An oriented linear chord diagram of $C_{7,2}$

embedded in a surface of genus g with one boundary component. We simply use chord slides to compute the intersection numbers and find the matrix T such that $(c_1, c_2, \ldots, c_{2g})^t T$ is a symplectic basis of $H_1(X; \mathbb{Z})$.

For the oriented linear chord diagram, we define a chord slide of c_i along c_j for the same position by the transformation from $(c_1, c_2, \ldots, c_{2g})$ to $(c'_1, c'_2, \ldots, c'_{2g})$ such that

$$c'_{k} = \begin{cases} c_{j} + c_{i} & (k = i) \\ c_{k} & (k \neq i). \end{cases}$$

as homology classes. For the *opposite position*, the c'_i is replaced with $c_j - c_i$. We define the *position* of a chord slide of c_i along c_j in the linear chord diagram. It is *same position* that the origin(terminal) point of the sliding chord c_i goes to the origin(terminal) point of the slided chord c_j . The others are *opposite position*. We remark the position does not depend on the orientation of chords. See Figure 4 and 5.

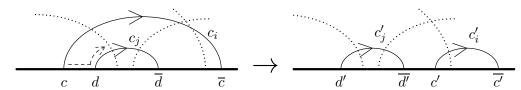


FIGURE 4. A chord slide of c_i along c_j for the same position

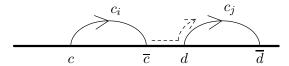


FIGURE 5. A chord slide for the opposite position

For $i \neq j$, let $M_s(\alpha, \beta)$ and $M_o(\alpha, \beta)$ denote the matrices whose (i, j)-th entries are -1 and 1 respectively for $(i, j) = (\alpha, \beta)$ and $\delta_{i,j}$ for $(i, j) \neq (\alpha, \beta)$. Here $\delta_{i,j}$ is Kronecker's delta. After a chord slide of c_i along c_j for the same position, we have

$$(c'_1, c'_2, \dots, c'_{2g}) = (c_1, c_2, \dots, c_{2g})^t M_s(i, j).$$

For the opposite position, ${}^tM_s(i,j)$ may be replaced with ${}^tM_o(i,j)$. Let $s_{i,j}(A)$ and $o_{i,j}(A)$ denote the matrices $M_s(i,j)A^tM_s(i,j)$ and $M_o(i,j)A^tM_o(i,j)$ respectively. By seeing the change of the intersection numbers of the chords $(c_1, c_2, \ldots, c_{2g})$, we have

Proposition 2.1. We consider loops $\{c_k\}_{k=1,2,...,2g}$ as chords in the oriented liner chord diagram and A its intersection matrix. If we slide c_i along c_j for the same position, the intersection matrix of $\{c'_k\}_{k=1,2,...,2g}$ is $s_{i,j}(A)$. For the opposite position, it is $o_{i,j}(A)$.

Using this proposition, we have only to deform the intersection matrix into a $2g \times 2g$ symplectic matrix $\begin{pmatrix} O & I_g \\ -I_g & O \end{pmatrix}$. Here I_g is the identity matrix of size g.

For the Klein quartic $C_{7,2}$, we have the matrices $s_{4,2} \circ s_{5,3} \circ o_{5,1} \circ o_{5,3} \circ o_{2,5} \circ s_{5,3}(A)$ and $M = M_s(4,2)M_s(5,3)M_o(5,1)M_o(5,3)M_o(2,5)M_s(5,3)$

$$\begin{pmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 1 & -1 & 0 \\ 1 & 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

respectively. We denote $(c_1, c_2, \ldots, c_6)^t M$ by $(c'_1, c'_2, \ldots, c'_6)$. Interchange $\{c'_3, c'_4\}$ and $\{c'_5, c'_6\}$, i.e., two rows $R_3 \leftrightarrow R_4$ and $R_5 \leftrightarrow R_6$ of M. The resulting matrix is denoted by $T_{7,2}$. We have the following matrices $T_{7,2}$ and $T_{7,2}A^tT_{7,2}$ then we obtain a symplectic basis $(a_1, a_2, a_3, b_1, b_2, b_3) = (c_1, c_2, \ldots, c_6)^t T_{7,2}$

$$T_{7,2} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & -1 & 0 & 1 & 0 \end{pmatrix}, \ T_{7,2}A^{t}T_{7,2} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \end{pmatrix}.$$

The matrix $T_{7,2}$ is different from one of [17].

2.5. **Period matrices.** We introduce a method for calculating the period matrix of X using holomorphic 1-forms of Bennama and Carbonne [5]. We compute those of $C_{7,1}$ and $C_{7,2}$.

Let $H^{1,0}(X)$ be the space of the holomorphic 1-forms on X. The floor function is denoted by $\lfloor \cdot \rfloor$. For $n = 1, 2, \ldots, p - 1 (= 2g)$, we define α_l and α_m by $\left\lfloor \frac{nl}{p} \right\rfloor$ and $\left\lfloor \frac{nm}{p} \right\rfloor$ respectively. Set $d_n = \left\lfloor \frac{n(l+m)}{p} \right\rfloor - \alpha_l - \alpha_m - 1$. Bennama and Carbonne [5] obtained that a basis of $H^{1,0}(X)$ is

$$\omega_{n,d} = \frac{x^{\alpha_l}(1-x)^{\alpha_m}x^d}{y^n}$$
 with $0 \le d \le d_n$ and $1 \le n \le p-1$.

Take a symplectic basis $\{a_i,b_i\}_{i=1,2,\dots,g}$ of $H_1(X;\mathbb{Z})$, *i.e.*, their intersection numbers are $a_i \cdot b_j = \delta_{i,j}$ and $a_i \cdot a_j = b_i \cdot b_j = 0$. Here $\delta_{i,j}$ is Kronecker's delta. We define two $g \times g$ matrices Ω_A and Ω_B by $\left(\int_{a_j} \omega_i\right)_{i,j}$ and $\left(\int_{a_j} \omega_i\right)_{i,j}$. It is known that the period matrix with respect to $\{a_i,b_i\}_{i=1,2,\dots,g}$ is obtained by $\Omega_A^{-1}\Omega_B$. See [12] for example.

We explain the case $C_{7,1}$ and $C_{7,2}$. For k=1,2, we define a basis $\omega_1^k, \omega_2^k, \omega_3^k$ of $H^{1,0}(C_{7,k})$ as follows:

Let B(u, v) be the beta function $\int_0^1 t^{u-1} (1-t)^{v-1} dt$ for u, v > 0. Put $(h_1, h_2, h_3, h_4) = (1/7, 2/7, 4/7, 1/7)$. From the equation $\int_{I_0} \omega_i^k dx = B(h_i, h_{i+k-1})$, we have

Lemma 2.2.

$$\int_{c_j} \omega_i^k = B(h_i, h_{i+k-1}) \left\{ \begin{array}{ll} (1 - \zeta_7^{ij}) & (k=1), \\ (1 - \zeta_7^{7h_i j}) & (k=2). \end{array} \right.$$

Remark 2.3. These integrals depend only on the cohomology class of ω_i^k and the homology class of c_i .

For k=1,2, let A_k and B_k be the 3×3 matrices $\left(\int_{a_j}\omega_i^k\right)_{i,j}$ and $\left(\int_{b_j}\omega_i^k\right)_{i,j}$ respectively. We have the equation as 3×6 matrices

$$(A_k, B_k) = \left(\int_{c_j} \omega_i^k\right)_{i,j} {}^t T_{7,k}.$$

Here we denote $T_{7,1} = T$ for the case p = 7 in Section 3. We have the period matrix of $C_{7,k}$.

Theorem 2.4. Let $\tau_{7,k}$ be the period matrix $A_k^{-1}B_k$ of $C_{7,k}$. Then we have

$$\tau_{7,1} = \begin{pmatrix} -\zeta^5 & -2 - \zeta^2 - \zeta^4 - \zeta^5 & \zeta + \zeta^3 + \zeta^5 \\ -2 - \zeta^2 - \zeta^4 - \zeta^5 & \zeta + 2\zeta^3 - \zeta^4 + \zeta^5 & 1 + \zeta^2 + \zeta^3 + \zeta^5 \\ \zeta + \zeta^3 + \zeta^5 & 1 + \zeta^2 + \zeta^3 + \zeta^5 & \zeta^2 \end{pmatrix}$$

and

$$\tau_{7,2} = \frac{1}{16} \begin{pmatrix} 7 + 5\sqrt{-7} & 5 - \sqrt{-7} & 10 - 2\sqrt{-7} \\ 5 - \sqrt{-7} & 7 + 5\sqrt{-7} & 6 + 2\sqrt{-7} \\ 10 - 2\sqrt{-7} & 6 + 2\sqrt{-7} & -4 + 4\sqrt{-7} \end{pmatrix},$$

where $\zeta = \zeta_7$.

We remark that we use the equation $\zeta_7 + \zeta_7^2 + \zeta_7^4 = (-1 + \sqrt{-7})/2$ for the computation of $\tau_{7,2}$.

3. Two symplectic bases of a kind of hyperelliptic curves

For odd integer $q \geq 5$, let $C_{q,1}$ be a plane algebraic curve defined by the affine equation $y^q = x(1-x)$. We obtain two symplectic bases of the first integral homology group $H_1(C_{q,1};\mathbb{Z})$. By substituting $y = \sqrt[q]{\frac{1}{4}}z$ and $x = \frac{\sqrt{-1}w-1}{2}$ into the above equation, we have $w^2 = z^q - 1$. So, it is a hyperelliptic curve of genus g = (q-1)/2. Set

the order q holomorphic automorphism $\sigma(x,y)=(x,\zeta y)$ with $\zeta=\zeta_q=\exp(2\pi\sqrt{-1}/q)$. Using these coordinates z and w, we define a loop $\gamma_k\colon [0,1]\to C_{q,1}, k=0,1,\ldots,2g$, by

$$\gamma_k(t) = \begin{cases} (\zeta^k \cdot 2t, \sqrt{-1}\sqrt{1 - (2t)^p}) & (0 \le t \le 1/2), \\ (\zeta^k(2 - 2t), -\sqrt{-1}\sqrt{1 - (2 - 2t)^p}) & (1/2 \le t \le 1). \end{cases}$$

We define the path $I_0: [0,1] \to C_{q,1}$ similarly in Subsection 2.1. It is easy to prove

Lemma 3.1. For k = 0, 1, ..., 2g, we have two paths $(\sigma_*)^k I_0$ and γ_k are homotopic with relative endpoints.

We introduce a well-known fact. See [1] for example.

Proposition 3.2. For i = 1, 2, ..., g, we denote $A_i = \gamma_{2i-1} \cdot \gamma_{2i}^{-1}$ and $B_i = \gamma_{2i-1} \cdot \gamma_{2i-2}^{-1} \cdot ... \cdot \gamma_1 \cdot \gamma_0^{-1}$. Then we have $\{A_i, B_i\}_{i=1,2,...,g}$ is a symplectic basis of $H_1(C_{q,1}; \mathbb{Z})$.

We call this basis a natural type. In fact, this proposition immediately follows from a two-sheeted covering $C_{q,1} \ni (z,w) \to z \in \mathbb{C}P^1$ branched over 2g+2 points $\{1,\zeta,\zeta^2,\ldots,\zeta^{2g},\infty\} \subset \mathbb{C}P^1$. We find another symplectic basis of $H_1(C_{q,1};\mathbb{Z})$. Although q is not prime in general, the method of the previous section can be applied to $C_{q,1}$ similarly. We recall $c_i = I_0 \cdot (\sigma_*)^i I_0^{-1}$. Using the oriented linear chord diagram in Figure 6, we have the the intersection numbers of c_i 's

$$c_i \cdot c_j = \begin{cases} 1 & (i < j) \\ 0 & (i = j) \\ -1 & (i > j) \end{cases}$$

Lemma 3.3. Let $M = (c_i \cdot c_j)_{i,j}$ be the intersection matrix of c_i 's. Then, the $2g \times 2g$ matrix

$$s_{2,4} \circ s_{4,6} \circ \cdots \circ s_{2g-2,2g} \circ o_{3,2} \circ o_{4,3} \circ \cdots \circ o_{2g,2g-1}(M)$$

equal to the $2g \times 2g$ -matrix

$$\begin{pmatrix} J & & O \\ & J & & \\ & & \ddots & \\ O & & & J \end{pmatrix},$$

where
$$J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$
.

Proof. It is enough only to explain from Figure 6 to Figure 8 via Figure 7. In Figure 6, we first take a chord slide c_{2g} along c_{2g-1} for an opposite position. Similarly, we take chord slides c_{2g-1} along c_{2g-2}, \ldots , and c_3 along c_2 for opposite positions. We obtain Figure 7. Endpoints series in this figure are

$$1, \overline{3}, 2, \overline{4}, 3, \overline{5}, 4, \overline{6}, 5, \dots, \overline{2i+1}, 2i, \overline{2i+2}, 2i+1, \dots, \overline{2q-1}, 2q-2, \overline{2q}, 2q-1, 1, 2.$$

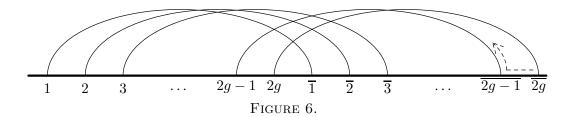
Next we take chord slides c_{2g-2} along c_{2g} , c_{2g-2} along c_{2g-4} ,..., and c_2 along c_4 for same positions. Finally, we have Figure 8. Endpoints series in this figure are

$$1,\overline{3},4,3,\overline{5},6,5,\ldots,\overline{2i+1},2i,\overline{2i+1},\ldots,\overline{2g-1},\overline{2g},2g-1,2g,2g-2,\ldots,2i,\ldots,2,\overline{1},\overline{2}.$$

We show the intersection matrices M, $o_{3,2} \circ o_{4,3} \circ o_{5,4} \circ o_{6,5}(M)$, and $s_{2,4} \circ s_{4,6} \circ o_{3,2} \circ o_{4,3} \circ o_{5,4} \circ o_{6,5}(M)$ corresponding to Figure 6, 7, and 8 respectively for the case g = 3.

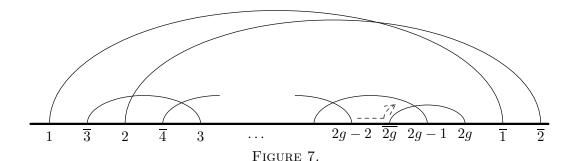
$$\begin{pmatrix}
0 & 1 & 1 & 1 & 1 & 1 \\
-1 & 0 & 1 & 1 & 1 & 1 \\
-1 & -1 & 0 & 1 & 1 & 1 \\
-1 & -1 & -1 & 0 & 1 & 1 \\
-1 & -1 & -1 & -1 & -1 & 0 & 1 \\
-1 & -1 & -1 & -1 & -1 & 0
\end{pmatrix}, \qquad
\begin{pmatrix}
0 & 1 & 0 & 0 & 0 & 0 \\
-1 & 0 & 1 & 0 & 0 & 0 \\
0 & -1 & 0 & 1 & 0 & 0 \\
0 & 0 & -1 & 0 & 1 & 0 \\
0 & 0 & 0 & -1 & 0 & 1 \\
0 & 0 & 0 & 0 & -1 & 0
\end{pmatrix},$$

and
$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & -1 & 0 \end{pmatrix}.$$



Let $c'_1, c'_2, \ldots, c'_{2g}$ be a basis of $H_1(C_{q,1}; \mathbb{Z})$ obtained by the above Lemma. We interchange this basis, then we have a symplectic basis

$$(a_1,\ldots,a_g,b_1,\ldots,b_g)=(c_1',c_3',\ldots,c_{2g-1}',c_2',c_4',\ldots,c_{2g}').$$



We interchange the raws of the matrix

$$M_s(2,4)M_s(4,6)\cdots M_s(2g-2,2g)M_o(3,2)M_o(4,3)\cdots M_o(2g,2g-1)$$

in the following way. All the odd raws move to $1, 2, \ldots, g$ -th ones and even $g + 1, g + 1, \ldots, g$ -th ones are given by the following way. $2, \ldots, 2g$. This resulting matrix is denoted by T.

Theorem 3.4. Set $(a_1, \ldots, a_g, b_1, \ldots, b_g) = (c_1, c_2, \ldots, c_{2g})^t T$. Then, $\{a_i, b_i\}_{i=1}^g$ is a symplectic basis of $H_1(C_{q,1}; \mathbb{Z})$.

Remark 3.5. Let $\vec{t_i}$ be the raw vector component of T for $i = 1, 2, \dots, 2g$. Then we have

$$\vec{t_i} = \begin{cases} (1,0^{2g-1}) & (i=1) \\ (0^{2i-3},-1,1,0^{2(g-i)+1}) & (i=2,3,\dots,g) \\ (0,1,(-1,1)^{g-1}) & (i=g+1) \\ (0^{2(i-1)},(-1,1)^{g-i+1}) & (i=g+2,g+3,\dots,2g) \end{cases}$$
 Here we denote $0^n = \underbrace{0,0,\dots,0}_n$ and $(-1,1)^m = \underbrace{-1,1,-1,-1,\dots,-1,1}_m$.

We prove that two symplectic bases $\{A_i, B_i\}_{i=1,2,\ldots,g}$ and $\{a_i, b_i\}_{i=1,2,\ldots,g}$ are different. From Lemma 3.1, we have the matrix K such that $(A_1, \ldots, A_g, B_1, \ldots, B_g) =$ $(c_1, c_2, \ldots, c_{2q})^t K$

$$K = \begin{pmatrix} -1 & 1 & 0 & & \cdots & & 0 \\ 0 & 0 & -1 & 1 & 0 & \cdots & 0 \\ & & & \vdots & & & \\ 0 & \cdots & & 0 & -1 & 1 \\ -1 & 0 & \cdots & & & 0 \\ -1 & 1 & -1 & 0 & \cdots & & 0 \\ & & & \vdots & & & \\ -1 & 1 & -1 & 1 & \cdots & -1 & 0 \end{pmatrix}.$$

The sums of all the components of T and K are equal to g+1 and -g respectively. Then we have

Proposition 3.6. Two symplectic bases $\{A_i, B_i\}_{i=1,2,...,g}$ and $\{a_i, b_i\}_{i=1,2,...,g}$ are different.

4. Period matrices of a hyperelliptic curve

We compute the period matrix τ_g of $C_{q,1}$ with respect to a natural symplectic basis $\{A_i, B_i\}_{i=1,2,...,g}$ of $H_1(C_{q,1}; \mathbb{Z})$. Moreover, we obtain the rerlation between τ_g and Schindler's [13]. Set $\omega_i = \frac{dx}{y^{q-i}}$ for i = 1, 2, ..., g. Bennama [4] proved that $\{\omega_i\}_{i=1,2,...,g}$ is a basis of $H^{1,0}(C_{q,1})$. From Subsection 2.5, we have the period of ω_i along c_j

$$\int_{c_i} \omega_i = (1 - \zeta^{ij}) B(i/q, i/q).$$

For simplicity, we denote $\omega_i' = \omega_i/B(i/q,i/q)$. Two $g \times g$ matrices Ω_A and Ω_B are defined by $\left(\int_{A_j} \omega_i'\right)_{i,j}$ and $\left(\int_{B_j} \omega_i'\right)_{i,j}$ respectively. We have the equation as $g \times 2g$ matrices,

$$(\Omega_A, \Omega_B) = \left(\int_{c_j} \omega_i\right)^t K.$$

We have the matrices Ω_A and Ω_B of periods. Tashiro, Yamazaki, Ito, and Higuchi [16] obtained the same result.

Proposition 4.1.
$$\Omega_A = (\zeta^{i(2j-1)} - \zeta^{2ij})_{i,j} \text{ and } \Omega_B = \left(\sum_{k=0}^{2j-1} (-1)^{k+1} \zeta^{ik}\right)_{i,j}.$$

Let τ_g denote the period matrix of $C_{q,1}$ with respect to a natural symplectic basis $\{A_i, B_i\}_{i=1,2,...,g}$ of $H_1(C_{q,1}; \mathbb{Z})$. It is known that the matrix τ_g is obtained by $\Omega_A^{-1}\Omega_B$. In order to compute it, we introduce two lemmas. The diagonal matrix whose (i, i)-th entry is a_i denoted by $\operatorname{diag}(a_i)_i$.

Lemma 4.2. We have

$$\Omega_A = -\operatorname{diag}\left(-1 + \zeta^i\right)_i \operatorname{diag}\left(\zeta^i\right)_i \left(\zeta^{2i(j-1)}\right)_{i,j} and$$

$$\Omega_B = \operatorname{diag}\left(-1 + \zeta^i\right)_i \left(\sum_{k=0}^{j-1} \zeta^{2ik}\right)_{i,j}.$$

Remark 4.3. The matrix $(\zeta^{2i(j-1)})_{i,j}$ is called the Vandermonde matrix.

For variables x_1, x_2, \ldots, x_n , we denote by $\sigma_i(x_1, x_2, \ldots, x_n)$ the symmetric polynomial

$$\sum_{1 \le j_1 < \dots < j_i \le n} x_{j_1} \cdots x_{j_i}$$

for $1 \le i \le n$ and $\sigma_0(x_1, x_2, \dots, x_n) = 1$. Knuth [11, Excercise 40 in §1.2.3] pointed out the inverse matrix of a Vandermonde matrix.

Lemma 4.4. Let a_1, a_2, \ldots, a_n be distinct complex constants. We denote a Vander-monde matrix of size n by $V_n = \left(a_i^{j-1}\right)_{i,j}$. Then we have the inverse matrix of V_n is

$$V_n^{-1} = \left((-1)^{i-1} \frac{\sigma_{n-i}(a_1, \dots, \widehat{a_j}, \dots, a_n)}{\prod_{m=1, m \neq j}^n (a_m - a_j)} \right)_{i,j},$$

where the 'hat' symbol $\hat{}$ over a_j indicates that this element is deleted from the sequence a_1, \ldots, a_n .

From the above two lemmas, we have.

Theorem 4.5. We have the period matrix τ_g of $C_{q,1}$ with respect to the symplectic basis $\{A_i, B_i\}_{i=1,2,...,g}$

$$\tau_g = \left(\sum_{k=1}^g \frac{(-1)^{i+g}}{2g+1} (1 - \zeta^{2kj}) \sigma_{g-i}(\zeta^2, \zeta^4, \dots, \widehat{\zeta^{2j}}, \dots, \zeta^{2g}) \prod_{m=g-k+1}^{2g-k} (1 - \zeta^{2m}) \right)_{i,j}.$$

Proof. We compute $\Omega_A^{-1}\Omega_B$ as follows

$$\Omega_A^{-1} \Omega_B = -\left(\zeta^{2i(j-1)}\right)_{i,j}^{-1} \operatorname{diag}\left(\zeta^{-i}\right)_i \left(\sum_{k=0}^{j-1} \zeta^{2ik}\right)_{i,j} \\
= -\left(\zeta^{2i(j-1)}\right)_{i,j}^{-1} \left(\zeta^{-i} \frac{1-\zeta^{2ij}}{1-\zeta^{2i}}\right)_{i,j}.$$

From the equation

$$\left(\zeta^{2i(j-1)}\right)_{i,j}^{-1} = \left((-1)^{i-1} \frac{\sigma_{g-i}(\zeta^2, \zeta^4, \dots, \widehat{\zeta^{2j}}, \dots, \zeta^{2g})}{\prod_{m=1, m \neq j}^n (\zeta^{2m} - \zeta^{2k})}\right)_{i,j},$$

we have (i,j)-th entry of τ_q

$$\sum_{k=1}^g (-1)^i \frac{\sigma_{g-i}(\zeta^2, \zeta^4, \dots, \widehat{\zeta^{2j}}, \dots, \zeta^{2g})}{\prod_{m=1, m \neq k}^g (\zeta^{2m} - \zeta^{2k})} \frac{\zeta^{-k}(1 - \zeta^{2kj})}{1 - \zeta^{2k}}.$$

Using the following lemma, we obtain the theorem.

Lemma 4.6. With the notation as above, we have the equation

$$\frac{1}{\zeta^k (1 - \zeta^{2k}) \prod_{m=1, m \neq k}^g (\zeta^{2m} - \zeta^{2k})} = \frac{(-1)^g}{2g + 1} \prod_{m=q-k+1}^{2g-k} (1 - \zeta^{2m}),$$

for each k = 1, 2, ..., g.

Proof. We compute the denominator of the LHS

$$\begin{split} \zeta^k(1-\zeta^{2k}) \prod_{m=1, m \neq k}^g (\zeta^{2m}-\zeta^{2k}) &= \zeta^{k+2k(g-1)+2k}(\zeta^{-2k}-1) \prod_{m=1, m \neq k}^g (\zeta^{2(m-k)}-1) \\ &= (-1)^g \prod_{m=-k, m \neq 0}^{g-k} (1-\zeta^{2m}). \end{split}$$

The result immediately follows from this and the equation

$$\prod_{m=-k, m\neq 0}^{g-k} (1-\zeta^{2m}) \prod_{m=g-k+1}^{2g-k} (1-\zeta^{2m}) = \prod_{l=1}^{2g} (1-\zeta^l) = 2g+1.$$

Set $\zeta = \zeta_7$. We calculate τ_3 of $C_{7,1}$

$$\begin{pmatrix} -\zeta^5 & -1 - \zeta^2 - \zeta^4 - \zeta^5 & 1 + \zeta + \zeta^3 + \zeta^5 \\ -1 - \zeta^2 - \zeta^4 - \zeta^5 & 1 + \zeta + 2\zeta^3 - \zeta^4 + \zeta^5 & 2 + \zeta^2 + \zeta^3 + \zeta^5 \\ 1 + \zeta + \zeta^3 + \zeta^5 & 2 + \zeta^2 + \zeta^3 + \zeta^5 & 1 + \zeta^2 \end{pmatrix}.$$

In general, the period matrix depends only on the choice of a symplectic basis and the complex structure of a compact Riemann surface. Two period matrices τ_g and τ_g' obtained from the same compact Riemann surface if and only if there exists a symplectic matrix $\begin{pmatrix} P & Q \\ R & S \end{pmatrix} \in \operatorname{Sp}(2g,\mathbb{Z})$ such that $\tau_g' = (P + \tau_g R)^{-1}(Q + \tau_g S)$. Here P,Q,R, and S are $g \times g$ \mathbb{Z} -coefficient matrices.

The symplectic matrix $\begin{pmatrix} P & Q \\ R & S \end{pmatrix}$ for two period matrices of $C_{q,1}$ with respect to $\{a_i,b_i\}_{i=1,2,\ldots,g}$ and $\{A_i,B_i\}_{i=1,2,\ldots,g}$ is given by ${}^tK({}^tT)^{-1}$. We call it H. For g=3, this matrix can be computed as

$$H = \left(\begin{array}{cccc} P & Q \\ R & S \end{array}\right) = \left(\begin{array}{ccccc} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ -1 & 1 & 0 & -1 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 \end{array}\right) \in \operatorname{Sp}(6, \mathbb{Z}).$$

We have $\tau_{7,1} = (P + \tau_3 R)^{-1} (Q + \tau_3 S)$. The matrix H can be obtained similarly for g > 3. But the period matrix with respect to a symplectic basis $\{a_i, b_i\}_{i=1,2,...,g}$ is complicated.

We introduce Schindler's period matrix, denoted by τ_g^S , for the hyperelliptic curve defined by the affine equation $w_1^2 = z_1(z_1^{2g+1} - 1)$. It is denoted by $C'_{q,1}$ This is biholomorphic to $C_{q,1}$. For $i = 1, 2, \ldots, g$, elements t_i of the q-th cyclotomic field $\mathbb{Q}(\zeta)$ are defined as follows:

$$t_{1} = (-1)^{g} \zeta^{g^{2}} \qquad (i = 1),$$

$$t_{2} = t_{1} \left(1 - \frac{1}{1+\zeta} \right) \qquad (i = 2),$$

$$t_{i+1} = \frac{t_{1} (1 - \sum_{k=2}^{i} \zeta^{g-i+k-1} t_{k} t_{i-k+2})}{1+\zeta^{-i}} \quad (i = 2, 3, \dots, g-1).$$

Theorem 4.7 (Schindler [13]). The (i,j)-th entry of the period matrix τ_g^S is obtained by

$$s_{i,j} = 1 - \frac{1}{t_1} \sum_{k=1}^{i} t_k t_{j-i+k}$$

for $1 \le i \le j \le g$ and $s_{j,i}$ for $g \ge i > j \ge 1$.

If we set $z_1 = 1/z$ and $w_1 = \sqrt{-1} w/z^{g+1}$, we obtain the biholomorphism from $C'_{q,1}$ to $C_{q,1}$. This implies that a symplectic basis of Schindler [13] is given by

$$(A_g, A_{g-1}, \dots, A_1, B_g, B_{g-1}, \dots, B_1) = (A_1, A_2, \dots, A_g, B_1, B_2, \dots, B_g) \begin{pmatrix} L_g & O \\ O & L_g \end{pmatrix},$$

using the symplectic basis of natural type. Here the (i,j)-th entry of the $g\times g$ matrix L_g is 1 for i+j=g+1 and 0 otherwise. It immediately follows that $L_g^{-1}=L_g$ and $\begin{pmatrix} L_g & O \\ O & L_g \end{pmatrix} \in \operatorname{Sp}(2g,\mathbb{Z})$. Then we have

Proposition 4.8. The relation between two period matrices τ_g and τ_g^S is obtained by

$$\tau_q^S = L_g \tau_g L_g.$$

Acknowledgements. The author would like to thank Nariya Kawazumi and Takashi Taniguchi for their useful comments. This work was partially supported by JSPS KAKENHI Grant Number 21740057 and Fellowship for Research Abroad of Institute

of National Colleges of Technology. It also was done while he stayed at the Danish National Research Foundation centre of Excellence, QGM (Centre for Quantum Geometry of Moduli Spaces) in Aarhus University. He is very grateful for the warm hospitality of QGM.

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